# **Describing Motion**

The **position** of an object is given by the vector  $\vec{r} = (x, y, z)$ . We can denote a particular *component* of  $\vec{r}$  as *s*; that is, *s* stands for *x*, *y*, or *z* depending on the situation.

The **velocity** of an object is the *derivative* of the position with respect to time; it tells you have much the position changes with time:  $d\vec{x} = (dx + dx) dx$ 

$$\vec{v} = \frac{dr}{dt} = \left(\frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt}\right)$$

We can write one component of the velocity vector as

$$v_s = \frac{ds}{dt}$$

The **acceleration** of an object is the derivative of the velocity with respect to time; it tells you have much the velocity changes with time:  $d\vec{x} = d^2\vec{x}$ 

$$\vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2\vec{r}}{dt^2}$$

We can write one component of the acceleration vector as

$$a_s = \frac{dv_s}{dt}$$

#### **Model: Constant Acceleration**

If an object in moving in a straight line with approximately constant acceleration, we can model it as having constant acceleration.

Position: 
$$s_f = s_i + v_{is}\Delta t + \frac{1}{2}a_s\Delta t^2$$
  
Velocity:  $v_{fs} = v_{is} + a_s\Delta t$   
No time:  $v_{fs}^2 = v_{is}^2 + 2a_s\Delta s$   
 $s_i + \frac{s_i}{t_i} + \frac{s_f}{t_f} + \frac{v_{si}}{t_i} + \frac{v_{sf}}{t_i} + \frac{v_{sf}}{t_f} + \frac{v_{sf}}{t_i} + \frac{v_{sf}}{t_f} + \frac{v_{sf$ 

### Motion on an Inclined Plane

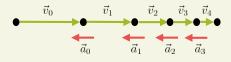
An object sliding (without friction) down an incline has a constant acceleration

 $a_s = \pm g \sin \theta$ 

where the plus or minus sign depends on the direction of the ramp.

## **Motion Diagrams**

A *motion diagram* shows a moving object simplified as a series of equally-spaced-in-time positions. Use five or six dots to indicate the positions when you're making one, and include the velocity and acceleration vectors.



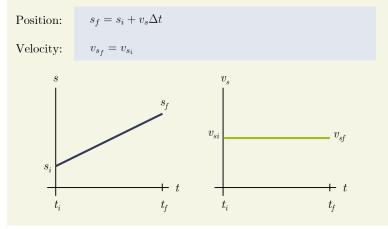
Example: motion diagram for a car slowing down.

#### The Particle Model

A *model* in physics is a simplified picture of reality that still captures the essence of the situation. We can model an object as a **particle** if its size and shape don't affect its motion. This model treats the object as though all of its mass is concentrated at a single point. In diagrams, we use a *dot* to represent a particle.

#### Model: Constant Velocity

If an object in moving in a straight line at approximately constant speed, we can model it as having *constant velocity*.



#### **Free Fall**

An object falling under the influence of *gravity* only is said to be in *free fall*. We can model the motion of the object as being in constant acceleration with

 $\vec{a}_{\text{free fall}} = (g, \text{vertically downward}),$ 

where the magnitude g of this free fall acceleration has the value

$$g = 9.80 \text{ m/s}^2$$

Note that, since g is a magnitude of a vector, it is a *positive* value.

# Mechanics